



链滴

# A 星寻路算法代码 --java 版 (A\* 搜索算法)

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来源网站: 链滴

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```

import java.util.*;

/**
 * @author sunze
 * @date 2020/10/26 4:55 下午
 */
public class Astar {

    /**
     * 公式：F=G+H
     *
     * 含义：G：起点到当前点的距离 H：当前点到终点的距离。
     *
     * F：等于前面两者之和，用于判定下一节点该往哪里走。如下图，此时，我们先不考虑障碍物先。
     */

    /**
     * 初始化地图
     */
    public static final String[][] MAP={
//      0 1 2 3 4 5 6 7 8
        /*0*/ { "0", "0", "0", "0", "0", "0", "0", "0", "0" },
        /*1*/ { "0", "0", "0", "0", "0", "0", "0", "0", "0" },
        /*2*/ { "0", "0", "0", "0", "0", "0", "0", "0", "0" },
        /*3*/ { "0", "0", "0", "1", "0", "0", "0", "0", "0" },
        /*4*/ { "0", "0", "0", "1", "0", "0", "0", "0", "0" },
        /*5*/ { "0", "0", "0", "1", "0", "0", "0", "0", "0" },
        /*6*/ { "0", "0", "0", "1", "0", "0", "0", "0", "0" },
        /*7*/ { "0", "0", "0", "1", "0", "0", "0", "0", "0" },
        /*8*/ { "0", "0", "0", "1", "0", "0", "0", "0", "0" }
    };

    /**
     * 横着走所需能量
     */
    public static final Integer HORIZONTAL_STEP= 10;
    /**
     * 斜着走所需能量
     */
    public static final Integer OBLIQUE_STEP= 14;

    /**
     * 可使用列表
     */
    public static List<Node> OPEN=new ArrayList<>();
    /**
     * 不可使用列表
     */
    public static List<Node> CLOSE=new ArrayList<>();

    private static final Node END_NODE=new Node(6,7);
    private static final Node START_NODE=new Node(7,1);

//    private static void

```

```

//      0 1 2 3 4 5 6 7 8
// /*0*/ { 0, 0, 0, 0, 0, 0, 0, 0, 0 },
// /*1*/ { 0, 0, 0, 0, 0, 0, 0, 0, 0 },
// /*2*/ { 0, 0, 0, 0, 0, 0, 0, 0, 0 },
// /*3*/ { 0, 0, 0, 1, 0, 0, 0, 0, 0 },
// /*4*/ { 0, 0, 0, 1, 0, 0, 0, 0, 0 },
// /*5*/ { 0, 0, 0, 1, 0, 0, 0, 0, 0 },
// /*6*/ { 0, 0, 0, 1, 0, 0, 0, 0, 0 },
// /*7*/ { 0, 0, 0, 0, 0, 0, 0, 0, 0 },
// /*8*/ { 0, 0, 0, 0, 0, 0, 0, 0, 0 }
public static void main(String[] args) {
    //将开始节点加入可使用列表
    START_NODE.parent=START_NODE;
    OPEN.add(START_NODE);
    while (CLOSE.indexOf(END_NODE)<0){
        //查找open中的F值最小的节点
        Node minFNodeInOpenList = OPEN.remove(0);
        //将这个节点放到close节点中
        CLOSE.add(0,minFNodeInOpenList);
        //获取这个节点周围的可移动节点并放入到open中
        findNeighborNodes(minFNodeInOpenList);
    }

    //回溯查找最短路径
    Node temp = CLOSE.get(0);
    List<Node> result = new ArrayList<>();
    while (temp.parent!=null&&temp!=temp.parent){
        result.add(0,temp);
        temp=temp.parent;
    }
    result.add(0,START_NODE);
    String[][] resultMap = MAP;
    for (Node node : result) {
        resultMap[node.x][node.y]="$";
    }
    showResult(resultMap);
    System.out.println("-----");
    String[][] tempMap = MAP;
    for (Node node : CLOSE) {
        System.out.println(node.x+":"+node.y);
        tempMap[node.x][node.y]="*";
    }
    showResult(tempMap);
}

private static void showResult(String[][] arr){
    for (int i = 0, j = 0; i < arr.length;) {
        System.out.print(arr[i][j]+ " ");
        j++;
        if (j >= arr[i].length) {
            i++;
            j = 0;
        }
        System.out.print("\n");
    }
}

```

```

    }
}
}

/**
 * 包括斜着周围一共有8个节点
 * @param currentNode
 */
public static void findNeighborNodes(Node currentNode) {
    List<Node> temp = new ArrayList<>();
    int x = currentNode.x;
    int y = currentNode.y;
    //
    for (int i=x-1>=0?x-1:0;i<=(x+1<=8?x+1:8);i++){
        for (int j=y-1>=0?y-1:0;j<=(y+1<=8?y+1:8);j++){
            //去除当前节点并且此节点不在close列表中
            if(!(i==x&&j==y)&&CLOSE.indexOf(new Node(i,j))<0&&OPEN.indexOf(new Node(i,j))<0){
                //去除障碍物
                if(MAP[i][j]!="1"){
                    //计算F值
                    Node node = new Node(i, j);
                    node.parent=currentNode;
                    int g = calcG(currentNode, node);
                    int h = calcH(END_NODE, node);
                    node.H=h;
                    node.G=g;
                    node.calcF();
                    temp.add(node);
                }
            }
        }
    }
    OPEN.addAll(temp);
    Collections.sort(OPEN);
}

private static int calcG(Node start, Node node) {
    if(start.x==node.x||start.y==node.y){
        return HORIZONTAL_STEP+node.parent.G;
    }else{
        return OBLIQUE_STEP+node.parent.G;
    }
}

/**
 * 这个是最简单粗暴的计算H值得方法，当然还有其它方法，这里先理解AStar的思想先，以后
 * 以自己改进这个计算H值得方法
 */
private static int calcH(Node end, Node node) {
    int step = Math.abs(node.x - end.x) + Math.abs(node.y - end.y);
    return step * HORIZONTAL_STEP;
}

```

```

public static class Node implements Comparable<Node>{
    public Node(int x, int y) {
        this.x = x;
        this.y = y;
    }

    public int x;
    public int y;

    public int F;
    public int G;
    public int H;

    public void calcF() {
        this.F = this.G + this.H;
    }

    public Node parent;

    @Override
    public boolean equals(Object o) {
        if (this == o) return true;
        if (o == null || getClass() != o.getClass()) return false;
        Node node = (Node) o;
        return x == node.x &&
            y == node.y;
    }

    @Override
    public int hashCode() {
        return Objects.hash(x, y);
    }

    @Override
    public int compareTo(Node o) {
        if(this.F > o.F){
            return 1;
        }
        if(this.F < o.F){
            return -1;
        }
        return 0;
    }
}
}

```

demo: <https://github.com/sunzeJAVA/AStar.git>